

FIG. 1

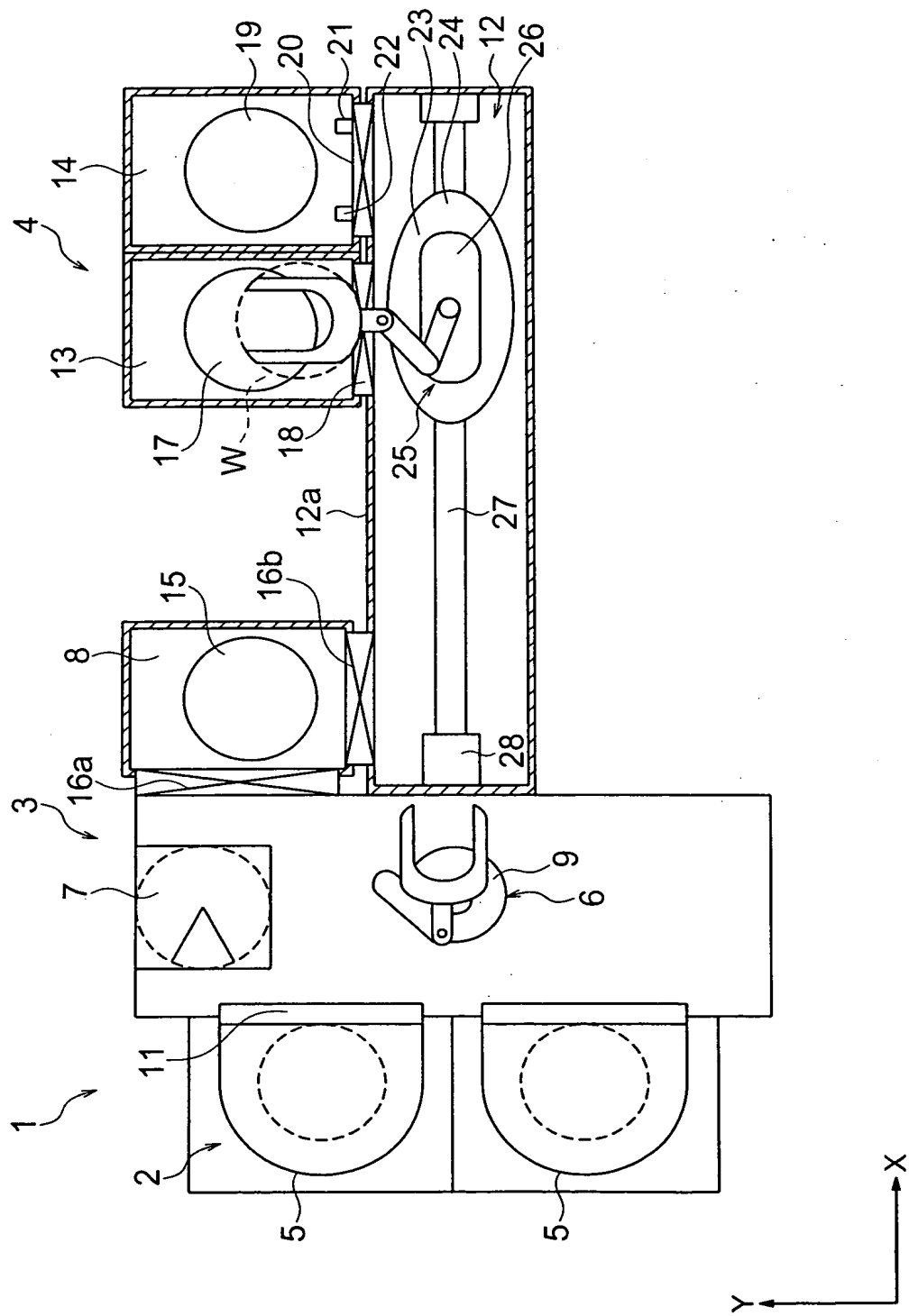


FIG. 2

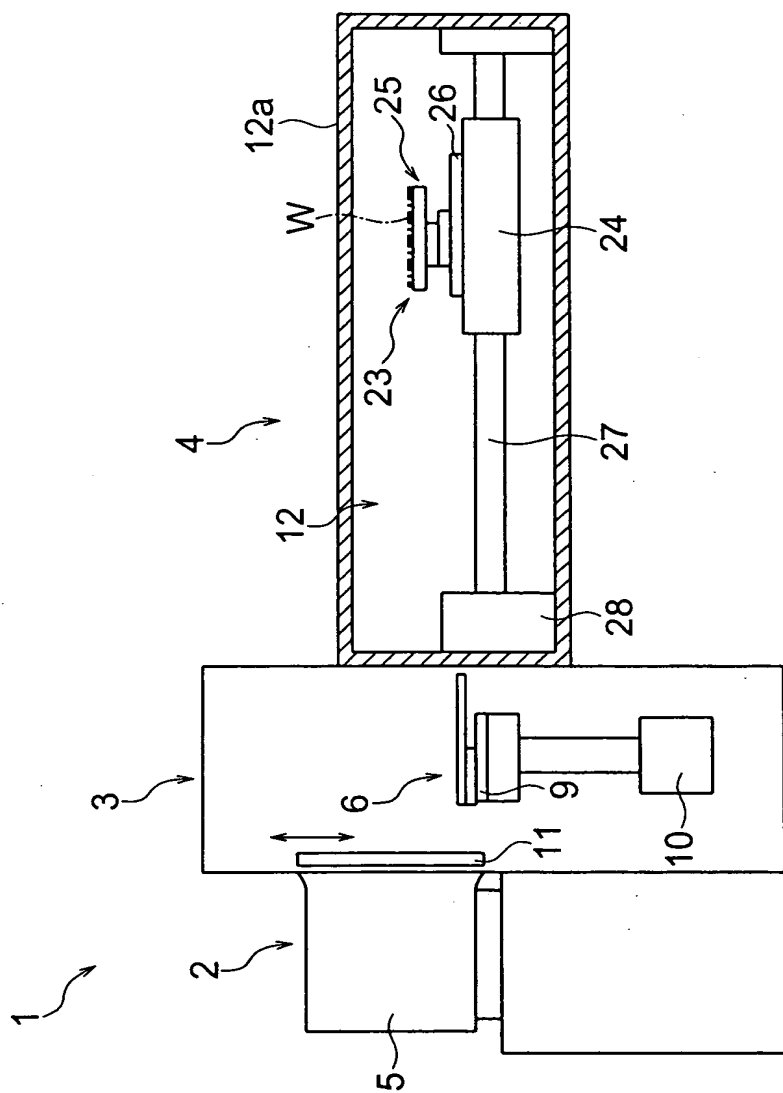


FIG. 3

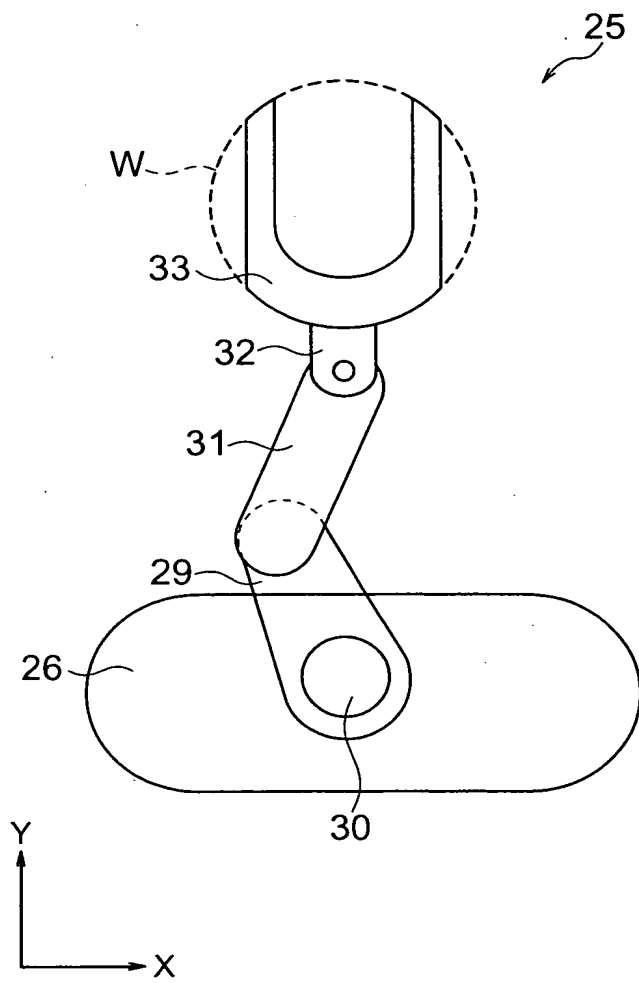




FIG. 5

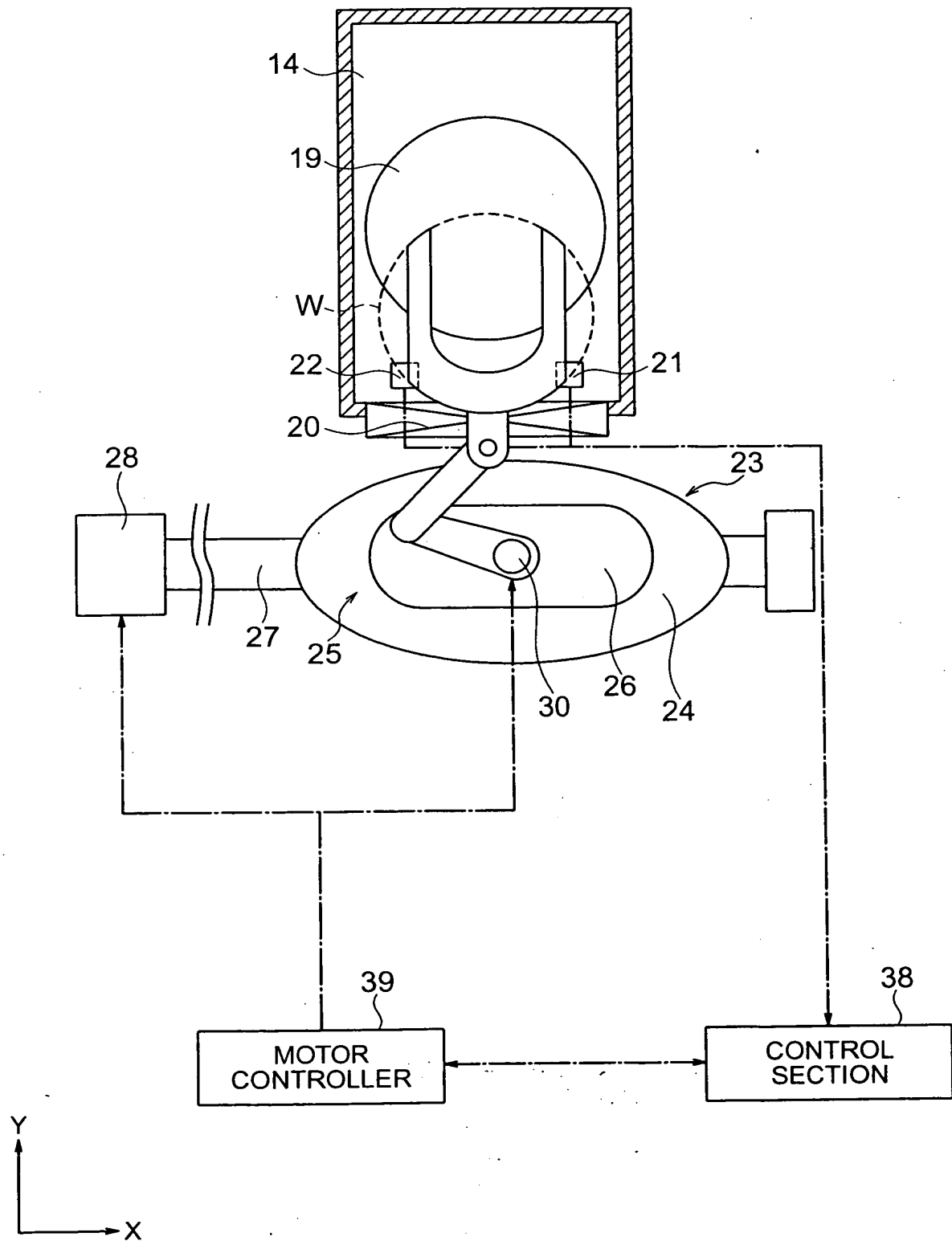


FIG. 6

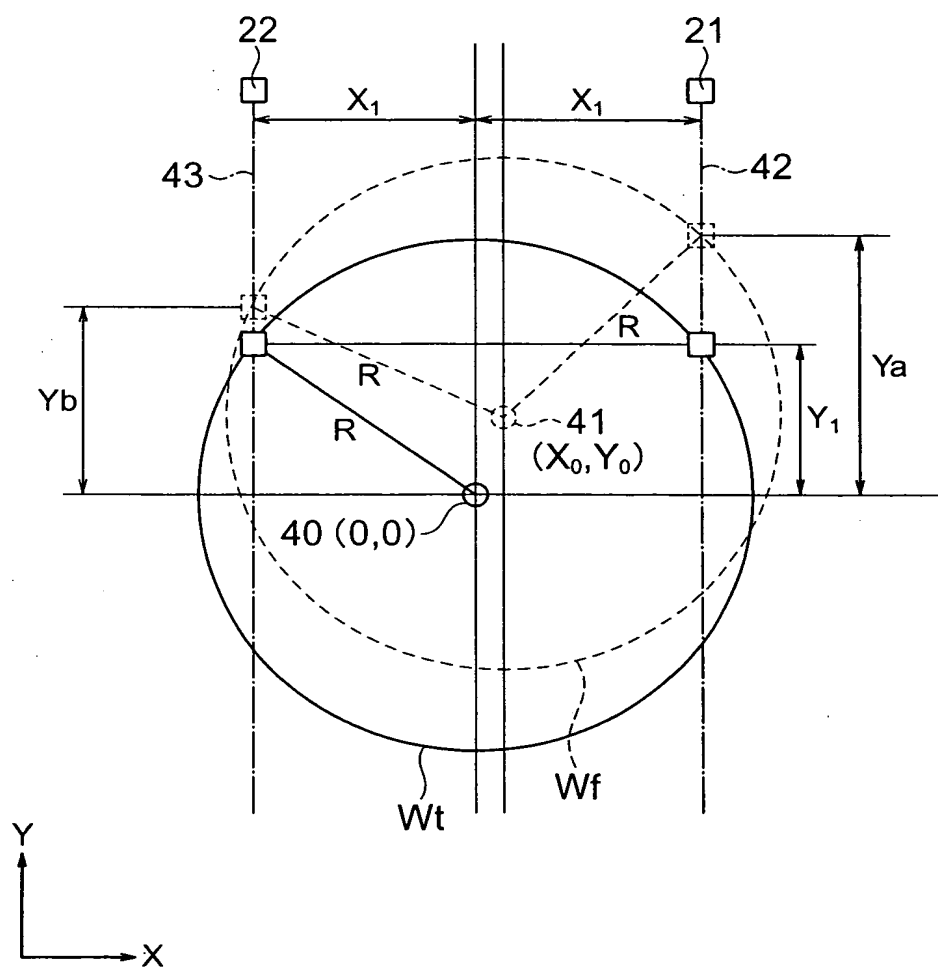


FIG. 7

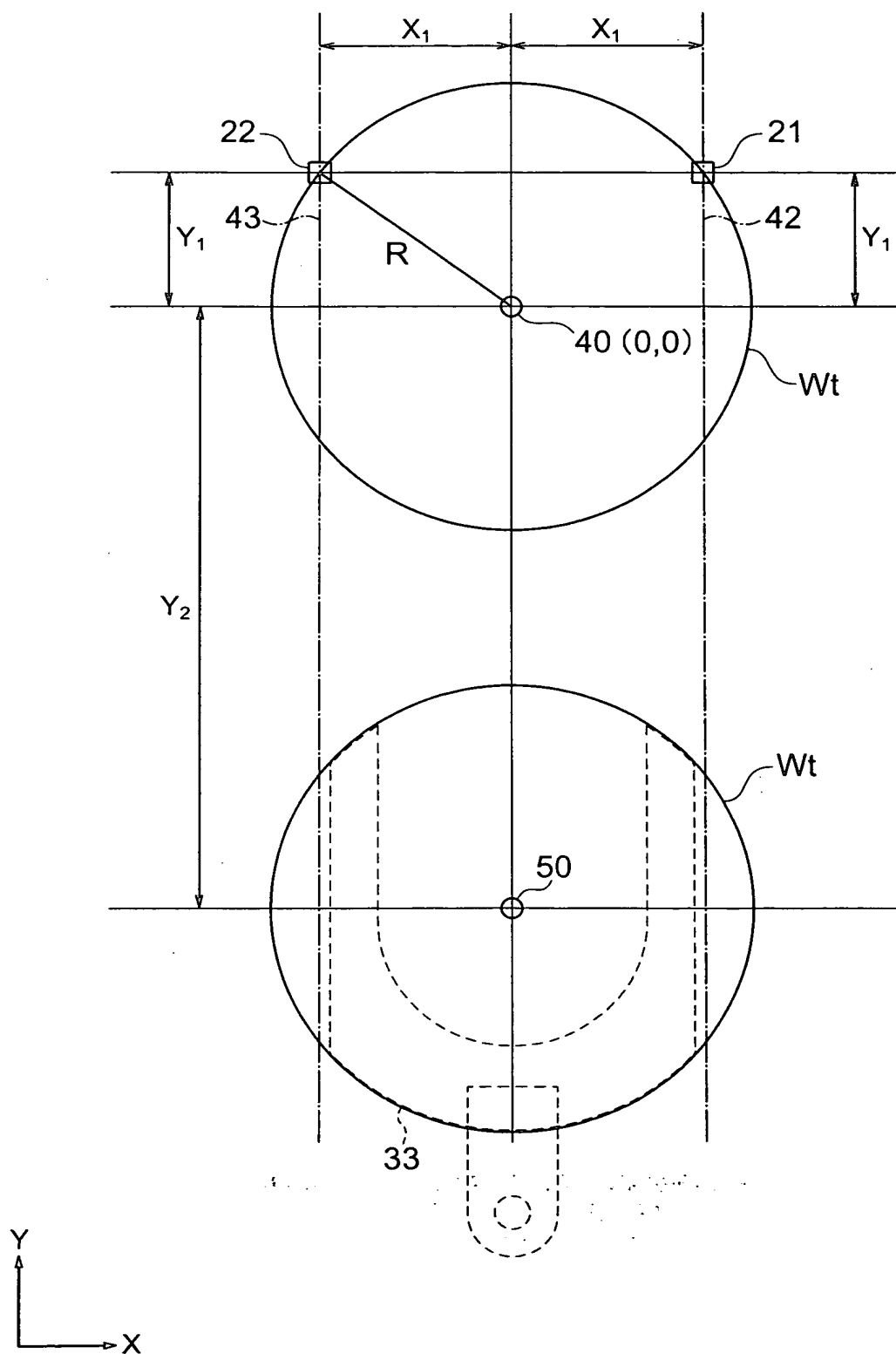


FIG. 8

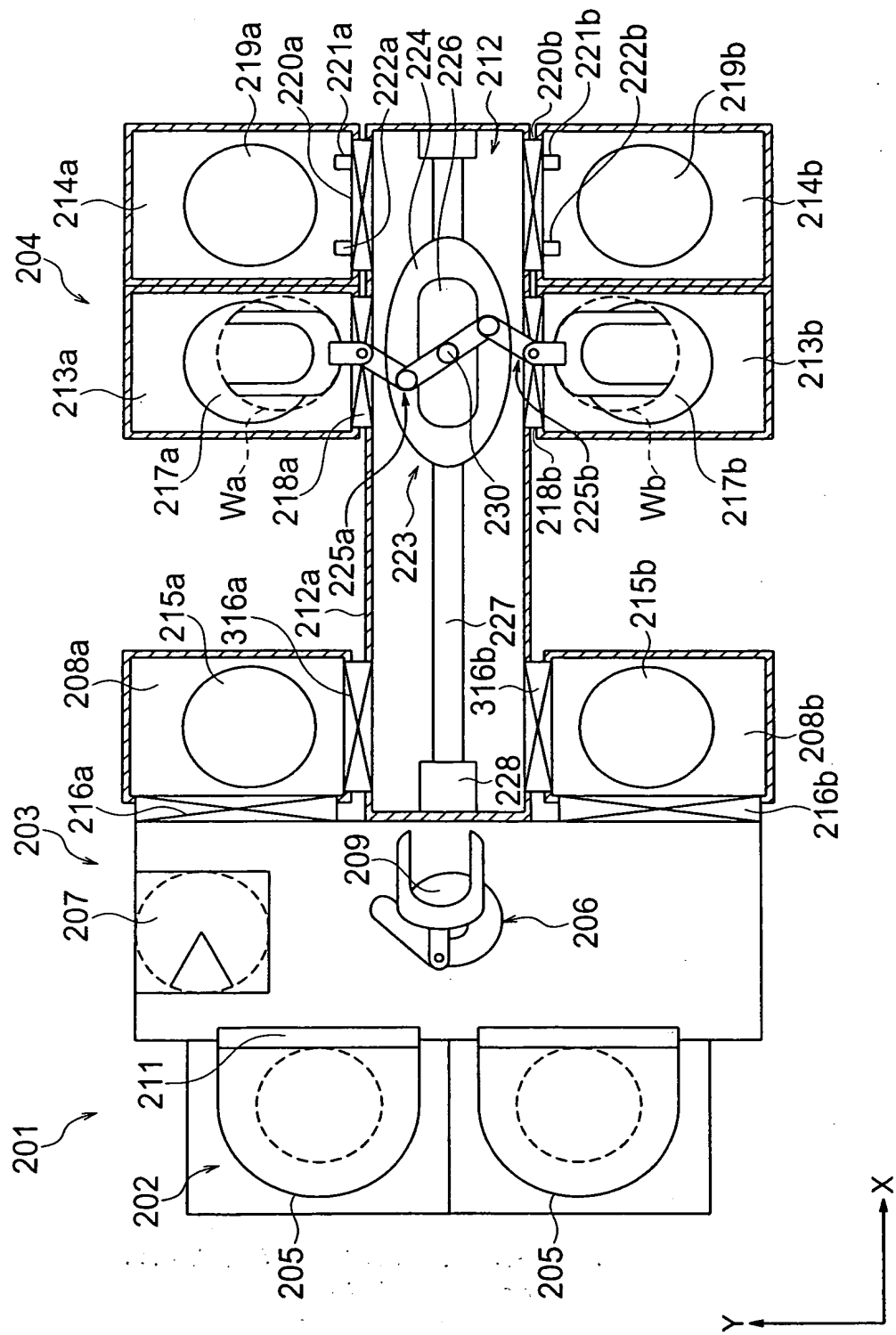




FIG. 9A

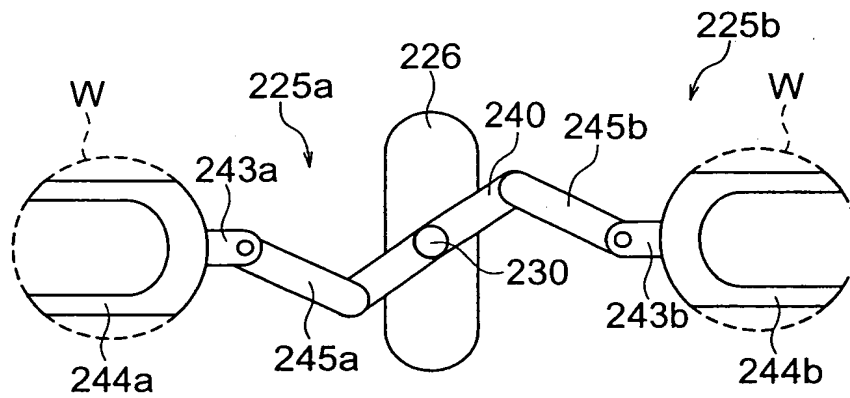


FIG. 9B

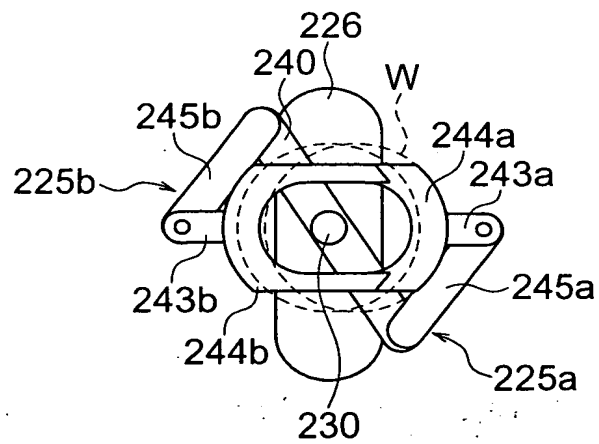


FIG. 10A

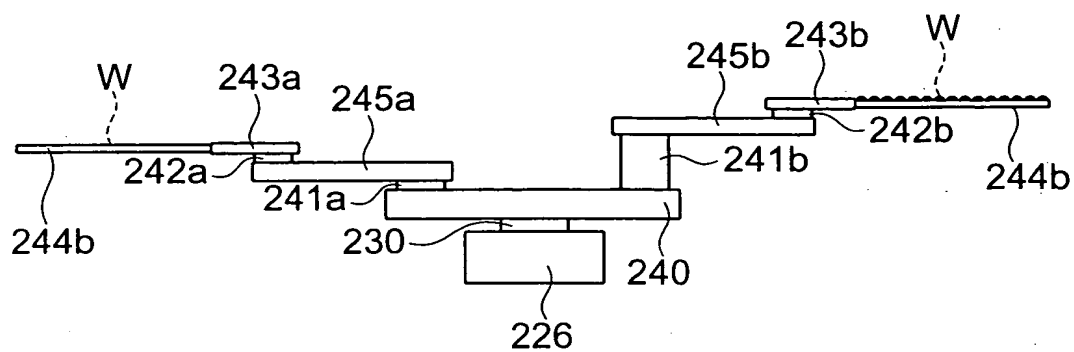


FIG. 10B

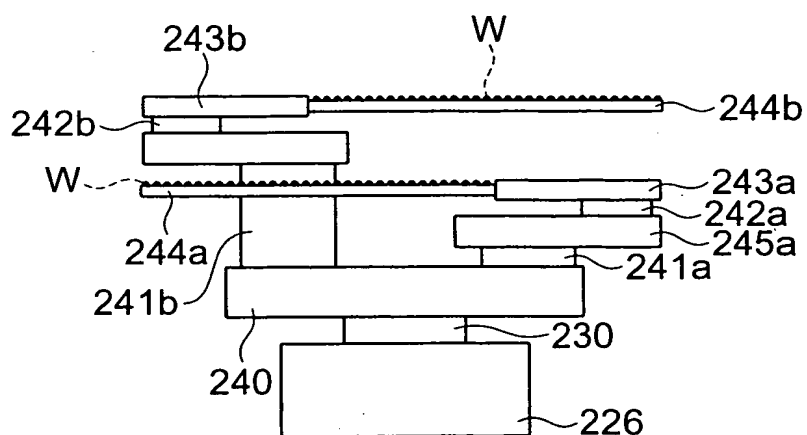
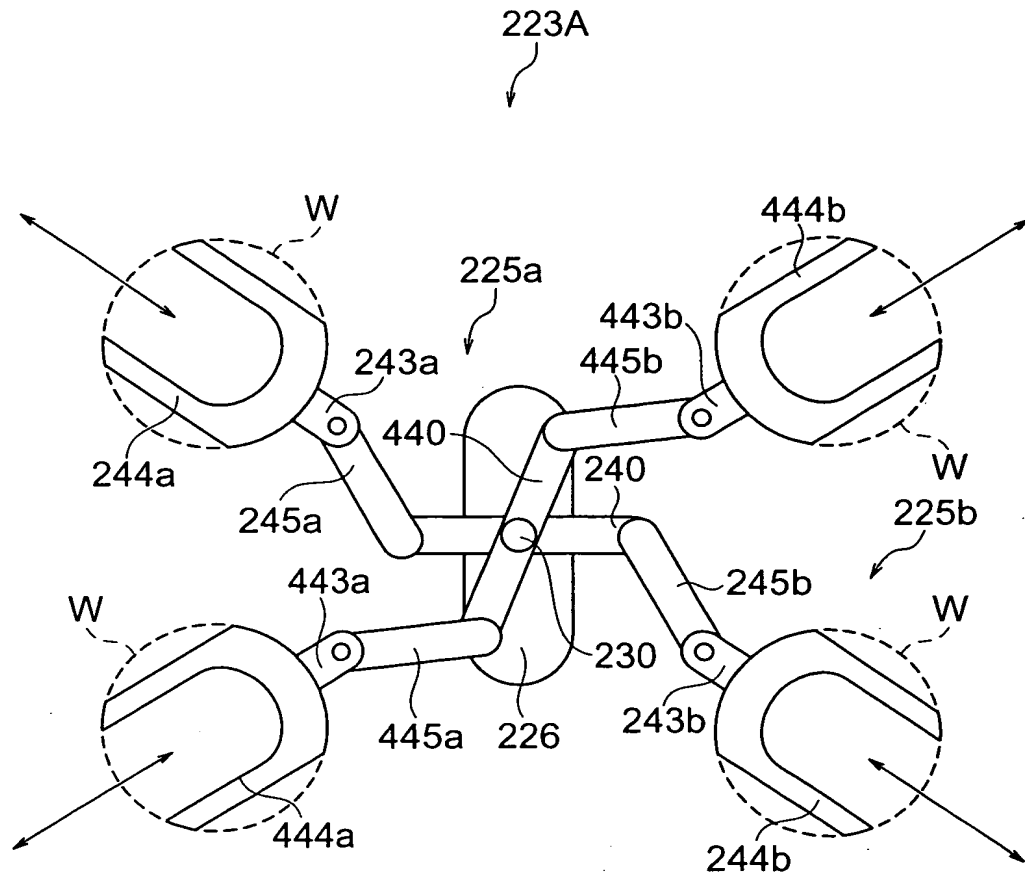


FIG. 11



[illegible]

Diagram illustrating a four-bar linkage mechanism. The mechanism consists of four links connected by revolute joints. The links are labeled 223A, 244a, 244b, and 444a. The joints are labeled 444a and 444b. The mechanism is shown in a planar configuration. A reference frame 3 is indicated by a coordinate system with x and y axes.

FIG. 14

